Damped Harmonic Oscillator - I

- Simple harmonic oscillator is an ideal case where there is frictional or opposing force. This can be achieved with ideally massless spring, very heavy bob, frictionless motion.
- The damping in harmonic oscillator (HO) happens due to friction.

We will consider here, a viscous drag affecting the damping.

Such that, $\vec{f} = -b\vec{v}$. Here, \vec{f} is the frictional force.

b is a proportionality constant that depends on the shape of the mass and the nedium through which it moves.

 \vec{v} is the instantaneous velocity.

Hence, total force $\vec{F} = \vec{F}_{spring} + \vec{f} = -k\vec{x} - b\vec{v}$.

The equation of motion: $m\ddot{x} = -kx - b\dot{x} \Rightarrow \ddot{x} + \gamma\dot{x} + \omega^2x = 0$

Here, $\gamma = b/m$ and $\omega^2 = k/m$

Solving Diff. Eqn. for dampled H.O.

The exponential ansatz states that a special solution to the differential equation takes the form:

$$x(t) = Ce^{\lambda t}$$

By forming the first and second derivations of (2) we obtain:

$$\dot{x}(t) = \lambda C e^{\lambda t} \ddot{x}(t) = \lambda^2 C e^{\lambda t}$$

By inserting the equations (2) and (3) into the differential equation (1) we obtain:

$$\lambda^2 C e^{\lambda t} + rac{\mu}{m} \lambda C e^{\lambda t} + rac{k}{m} C e^{\lambda t} = 0$$

Division by $Ce^{\lambda t}$ will simplify this to:

$$\lambda^2 + \frac{\mu}{m}\lambda + \frac{k}{m} = 0$$

This equation is also called the characteristic equation. It is a quadratic equation in normal form.

Damped Harmonic Oscillator - II

Hence, the *characteristic equation* can be written as: $\lambda^2 + \gamma \lambda + \omega^2 = 0$ $\Rightarrow \lambda = \frac{-\gamma \pm \sqrt{\gamma^2 - 4\omega^2}}{2}$

The particular solution for the equation can be noted as $x(t) = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t}$

One can write a general solution such as: $x(t) = Ae^{-\left(\frac{\gamma}{2}\right)t}\cos(\omega_1 t + \phi)$, where $\omega_1 = \sqrt{\omega^2 - \frac{\gamma^2}{4}}$ and ϕ is the phase.

Light Damping: $\gamma^2 \ll 4\omega^2$

- In this case, $\gamma^2 \ll 4\omega^2$, $x(t) = C_1 e^{-\frac{\gamma}{2}t + i\sqrt{\omega^2 \frac{\gamma^2}{4}}} + C_2 e^{-\frac{\gamma}{2}t i\sqrt{\omega^2 \frac{\gamma^2}{4}}}$
- •So, the solution will be oscillatory in nature, but the amplitude will be decaying exponentially.

Damped Harmonic Oscillator - III

Heavy Damping: $\gamma^2 > 4\omega^2$

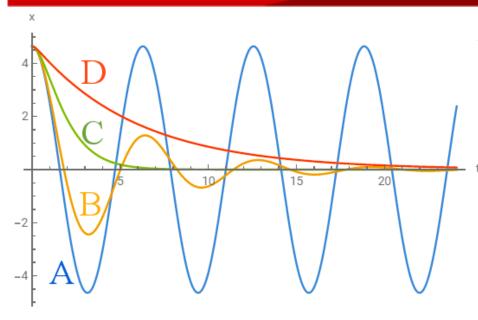
In this case,
$$x(t) = C_1 e^{\left(-\frac{\gamma}{2} + \frac{\gamma}{2}\sqrt{1 - \frac{4\omega^2}{\gamma^2}}\right)t} + C_2 e^{\left(-\frac{\gamma}{2} - \frac{\gamma}{2}\sqrt{1 - \frac{4\omega^2}{\gamma^2}}\right)t}$$

■The solution does not have any oscillatory behavior. The motion is known as overdamped.

Critical Damping: $\gamma^2 = 4\omega^2$

- In this case, $x(t) = Ce^{-\frac{\gamma t}{2}}$
- •However, the solution is incomplete as a second order linear differential equation must contain two arbitrary constant. Hence, we consider $x(t) = u(t)e^{-\frac{\gamma}{2}t}$.
- •Substituting in the original equation, and using the fact $\gamma = 2\omega$ we find that u(t) must satisfy $\ddot{u} = 0$.
- •Hence, u(t) = a + bt
- So, the general solution will be: $x(t) = Ae^{-\frac{\gamma}{2}t} + Bte^{-\frac{\gamma}{2}t}$

Comparison



https://www.youtube.com/watch?v=99ZE2RGwqSM https://www.youtube.com/watch?v=sP1DzhT8Vzo https://beltoforion.de/en/harmonic_oscillator/

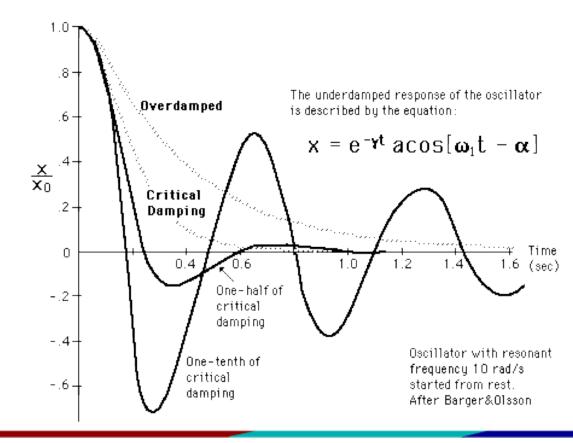
Lectures by Walter Lewin:

https://www.youtube.com/watch?v=tNpuTx7UQbw https://www.youtube.com/watch?v=77ZF50ve6rs A: Undamped

B: Under-damped

C: Critically damped

D: Over-damped



Damped Harmonic Oscillator - IV

•If we consider the oscillator is lightly damped, then we can assume

- •If the motion is lightly damped then $\frac{\gamma}{\omega_1} \ll 1$, thus $v(t) \simeq -\omega_1 A e^{-\frac{\gamma t}{2}} \sin(\omega_1 t + \phi)$
- •Hence, $K(t) = \frac{1}{2}mv^2 = \frac{1}{2}m\omega_1^2 A^2 e^{-\gamma t} \sin^2(\omega_1 t + \phi)$.
- The potential energy, $U(t) = \frac{1}{2}kx^2 = \frac{1}{2}kA^2e^{-\gamma t}\cos^2(\omega_1 t + \phi)$
- Therefore, the total energy $E(t) = \frac{1}{2}A^2e^{-\gamma t}[m\omega_1^2\sin^2(\omega_1t + \phi) + k\cos^2(\omega_1t + \phi)] = \frac{1}{2}kA^2e^{-\gamma t}$.
- •At t = 0, energy of the system is $E_0 = \frac{1}{2}kA^2$. Thus, $E(t) = E_0e^{-\gamma t}$
- This implies exponential decrease of energy in time.

Damped Harmonic Oscillator - V

Q of an Oscillator

- The degree of damping of an oscillator is often specified by a dimensionless parameter Q, known as quality factor.
- $Q = \frac{energy strored in the oscillator}{energy dissipated per radian}$
- In light damping case, $\frac{dE}{dt} = -\gamma E_0 e^{-\gamma t} = -\gamma E$
- •Hence, energy dissipated in a short time Δt is $\Delta E \sim \left| \frac{dE}{dt} \right| \Delta t = \gamma E \Delta t$
- •One radian of oscillation requires time $\Delta t = \frac{1}{\omega_1}$, and the energy dissipated $\frac{\gamma E}{\omega_1}$.
- $Q = \frac{E}{\gamma E/\omega_1} = \frac{\omega_1}{\gamma} \simeq \frac{\omega}{\gamma}.$
- •A lightly damped oscillator has $Q \gg 1$ where Q is low for heavily damped oscillator.
- \blacksquare An undamped oscillator has infinite Q.

Example

A paper weight suspended from a hefty rubber band has period of 1.2 s and the amplitude of oscillation decreased by a factor of 2 after three periods. Determine Q of this system.

From the theory of damped oscillator, we know that the amplitude can be expressed as, $Ae^{-\frac{\gamma}{2}t}$.

The ratio of the amplitude at t = 0 after three periods (when $t = 1.2 \times 3$ s = 3.6 s) is,

$$2 = \frac{Ae^0}{Ae^{-\frac{3.6\gamma}{2}}} \Rightarrow 1.8\gamma = \ln 2 = 0.69 \Rightarrow \gamma = 0.39s^{-1}.$$

Now,
$$\omega = \frac{2\pi}{T} = \frac{2\pi}{1.2} = 5.23 \text{ s}^{-1}$$
.

Hence,
$$Q = \frac{\omega}{\gamma} = 13.42$$